Update robot on cover  
Replace with “inertial state” with what it actually is

Present equations before referencing them

Remove asterisks from equations – use mathtype

Compression ratio – CR? Be consistent

Optical system typos  
We developed the models and matlab translated them to embedded code  
We need a conclusion 100% for sure

Update robot angle definitions

Remove title on plots, don’t have title and caption!

Justify the FEA – Element type/quality, forces, hand calculations

***The Control***

Mention the unity feedback loop used in control

Simulation -> desired thetas -> valves -> dynamics -> theta

Look into the valve transfer function (next quarter) [voltage to flow rate]

***Bill of Materials***

We have electronics, chassis, cylinders, feet

We NEED – bearings, brackets, legs, flexible tubing

Report draft – MONADY TO RODRIGUEZ  
Presentation draft – Wednesday at the latest

Logbooks – Week 1 of spring